

Eight Output Differential Buffer for PCle Gen 2

ICS9DB803DI

Description

The 9DB803 is a DB800 Version 2.0 Yellow Cover part with PCI Express Gen II support. It can be used in PC or embedded systems to provide outputs that have low cycle-to-cycle jitter (50ps), low output-to-output skew (100ps), and are PCI Express Gen 2 compliant. The 9DB803 supports a 1 to 8 output configuration, taking a spread or non spread differential HCSL input from a CK410(B) main clock such as 954101 and 932S401, or any other differential HCSL pair. 9DB803 can generate HCSL or LVDS outputs from 50 to 100MHz in PLL mode or 50 to 400Mhz in bypass mode. There are two dejittering modes available selectable through the HIGH_BW# input pin, high bandwidth mode provides de-jittering for spread inputs and low bandwidth mode provides extra de-jittering for non-spread inputs. The SRC_IN#, PD#, and individual OE realtime input pins provide completely programmable power management control.

Features/Benefits

- Spread spectrum modulation tolerant, 0 to -0.5% down spread and +/- 0.25% center spread.
- Supports undriven differential outputs in PD# and SRC_STOP# modes for power management.

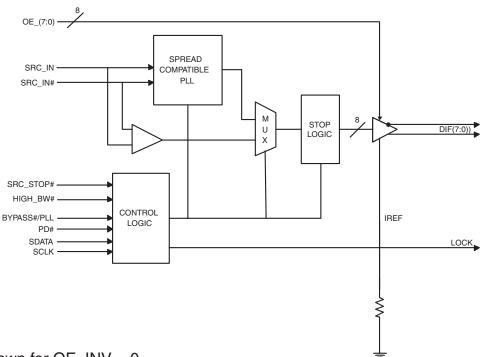
Output Features

- 8 0.7V current-mode differential output pairs
- · Supports zero delay buffer mode and fanout mode
- Bandwidth programming available

Key Specifications

- Outputs cycle-cycle jitter < 50ps
- Outputs skew: 50ps
- 50-100 MHz operation in PLL mode
- 50-400 MHz operation in Bypass mode
- Phase jitter: PCle Gen1 < 86ps peak to peak
- Phase jitter: PCIe Gen2 < 3.1ps rms
- 48-pin SSOP/TSSOP package
- Available in RoHS compliant packaging

Funtional Block Diagram



Note: Polarities shown for $OE_INV = 0$.

Pin Configuration

SRC_DIV# VDD GND SRC_IN# OE_0 OE_3 DIF_0# GND VDD DIF_1# OE_1 OE_2 DIF_2# GND VDD DIF_3 DIF_3#	3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20	47 46 45 44 43 42 41 40 39 38 37 36 35 34 33 32 31 30 29	VDDA GNDA IREF LOCK OE_7 OE_4 DIF_7 DIF_7# OE_INV VDD DIF_6 DIF_6 OE_5 DIF_5 DIF_5# GND VDD DIF_4 DIF_4 DIF_4# HIGH_BW#
DIF_3	20	29	DIF_4#
DIF_3# BYPASS#/PLL			HIGH_BW# DIF_STOP#
SCLK			PD#
SDATA			GND

 $OE_INV = 0$

SRC_DIV# 1	
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 $OE_INV = 1$

Polarity Inversion Pin List Table

	OE_INV				
Pins	0	1			
6	OE_0	OE0#			
7	OE_3	OE3#			
14	OE_1	OE1#			
15	OE_2	OE2#			
26	PD#	PD			
27	DIF_STOP#	DIF_STOP			
35	OE_5	OE5#			
36	OE_6	OE6#			
43	OE_4	OE4#			
44	OE_7	OE7#			

Power Groups

Pin N	Number	Deceriation
VDD	GND	Description
2	3	SRC_IN/SRC_IN#
6,11,19, 31,39	10,18, 25,32	DIF(7:0)
31,39	10, 10, 23,32	Dii (7.0)
N/A	47	IREF
48	47	Analog VDD & GND for PLL core

	N # PIN NAME PIN TYPE PEOPINTION					
PIN#	PIN NAME	PIN TYPE	DESCRIPTION			
1	SRC_DIV#	IN	Active low Input for determining SRC output frequency SRC or SRC/2. 0 = SRC/2, 1= SRC			
2	VDD	PWR	Power supply, nominal 3.3V			
3	GND	PWR	Ground pin.			
4	SRC_IN	IN	0.7 V Differential SRC TRUE input			
5	SRC_IN#	IN	0.7 V Differential SRC COMPLEMENTARY input			
6	OE_0	IN	Active high input for enabling output 0. 0 = tri-state outputs, 1= enable outputs			
7	OE_3	IN	Active high input for enabling output 3. 0 = tri-state outputs, 1= enable outputs			
8	DIF 0	OUT	0.7V differential true clock output			
9	DIF_0#	OUT	0.7V differential complement clock output			
10	GND	PWR	Ground pin.			
11	VDD	PWR	Power supply, nominal 3.3V			
12	DIF_1	OUT	0.7V differential true clock output			
13	DIF_1#	OUT	0.7V differential complement clock output			
14	OE_1	IN	Active high input for enabling output 1. 0 = tri-state outputs, 1= enable outputs			
15	OE_2	IN	Active high input for enabling output 2. 0 = tri-state outputs, 1= enable outputs			
16	DIF_2	OUT	0.7V differential true clock output			
17	DIF_2#	OUT	0.7V differential complement clock output			
18	GND	PWR	Ground pin.			
19	VDD	PWR	Power supply, nominal 3.3V			
20	DIF_3	OUT	0.7V differential true clock output			
21	DIF_3#	OUT	0.7V differential complement clock output			
22	BYPASS#/PLL	IN	Input to select Bypass(fan-out) or PLL (ZDB) mode 0 = Bypass mode, 1= PLL mode			
23	SCLK	IN	Clock pin of SMBus circuitry, 5V tolerant.			
24	SDATA	I/O	Data pin for SMBus circuitry, 5V tolerant.			

			PEOPLETION			
PIN#	PIN NAME	PIN TYPE	DESCRIPTION			
25	GND	PWR	Ground pin.			
26	PD#	IN	Asynchronous active low input pin used to power down the device. The internal clocks are disabled and the VCO and the crystal are stopped.			
27	DIF_STOP#	IN	Active low input to stop differential output clocks.			
28	HIGH_BW#	PWR	3.3V input for selecting PLL Band Width 0 = High, 1= Low			
29	DIF_4#	OUT	0.7V differential complement clock output			
30	DIF_4	OUT	0.7V differential true clock output			
31	VDD	PWR	Power supply, nominal 3.3V			
32	GND	PWR	Ground pin.			
33	DIF_5#	OUT	0.7V differential complement clock output			
34	DIF_5	OUT	0.7V differential true clock output			
35	OE_5	IN	Active high input for enabling output 5. 0 = tri-state outputs, 1= enable outputs			
36	OE_6	IN	Active high input for enabling output 6. 0 = tri-state outputs, 1= enable outputs			
37	DIF_6#	OUT	0.7V differential complement clock output			
38	DIF_6	OUT	0.7V differential true clock output			
39	VDD	PWR	Power supply, nominal 3.3V			
40	OE_INV	IN	This latched input selects the polarity of the OE pins. 0 = OE pins active high, 1 = OE pins active low (OE#)			
41	DIF_7#	OUT	0.7V differential complement clock output			
42	DIF_7	OUT	0.7V differential true clock output			
43	OE_4	IN	Active high input for enabling output 4. 0 = tri-state outputs, 1= enable outputs			
44	OE_7	IN	Active high input for enabling output 7. 0 = tri-state outputs, 1= enable outputs			
45	LOCK	OUT	3.3V output indicating PLL Lock Status. This pin goes high when lock is achieved.			
46	IREF	IN	This pin establishes the reference current for the differential current-mode output pairs. This pin requires a fixed precision resistor tied to ground in order to establish the appropriate current. 475 ohms is the standard value.			
47	GNDA	PWR	Ground pin for the PLL core.			
48	VDDA	PWR	3.3V power for the PLL core.			

PIN#	PIN NAME	PIN TYPE	DESCRIPTION
1	SRC_DIV#	IN	Active low Input for determining SRC output frequency SRC or SRC/2. 0 = SRC/2, 1= SRC
2	VDD	PWR	Power supply, nominal 3.3V
3	GND	PWR	Ground pin.
4	SRC_IN	IN	0.7 V Differential SRC TRUE input
5	SRC_IN#	IN	0.7 V Differential SRC COMPLEMENTARY input
6	OE0#	IN	Active low input for enabling DIF pair 0. 1 = tri-state outputs, 0 = enable outputs
7	OE3#	IN	Active low input for enabling DIF pair 3. 1 = tri-state outputs, 0 = enable outputs
8	DIF_0	OUT	0.7V differential true clock output
9	DIF_0#	OUT	0.7V differential complement clock output
10	GND	PWR	Ground pin.
11	VDD	PWR	Power supply, nominal 3.3V
12	DIF_1	OUT	0.7V differential true clock output
13	DIF_1#	OUT	0.7V differential complement clock output
14	OE1#	IN	Active low input for enabling DIF pair 1. 1 = tri-state outputs, 0 = enable outputs
15	OE2#	IN	Active low input for enabling DIF pair 2. 1 = tri-state outputs, 0 = enable outputs
16	DIF_2	OUT	0.7V differential true clock output
17	DIF_2#	OUT	0.7V differential complement clock output
18	GND	PWR	Ground pin.
19	VDD	PWR	Power supply, nominal 3.3V
20	DIF_3	OUT	0.7V differential true clock output
21	DIF_3#	OUT	0.7V differential complement clock output
22	BYPASS#/PLL	IN	Input to select Bypass(fan-out) or PLL (ZDB) mode 0 = Bypass mode, 1= PLL mode
23	SCLK	IN	Clock pin of SMBus circuitry, 5V tolerant.
24	SDATA	I/O	Data pin for SMBus circuitry, 5V tolerant.

PIN#	PIN NAME	PIN TYPE	DESCRIPTION			
25	GND	PWR	Ground pin.			
26	PD	IN	Asynchronous active high input pin used to power down the device. The internal clocks are disabled and the VCO is stopped.			
27	DIF_STOP	IN	Active High input to stop differential output clocks.			
28	HIGH_BW#	PWR	3.3V input for selecting PLL Band Width 0 = High, 1= Low			
29	DIF_4#	OUT	0.7V differential complement clock output			
30	DIF_4	OUT	0.7V differential true clock output			
31	VDD	PWR	Power supply, nominal 3.3V			
32	GND	PWR	Ground pin.			
33	DIF_5#	OUT	0.7V differential complement clock output			
34	DIF_5	OUT	0.7V differential true clock output			
35	OE5#	IN	Active low input for enabling DIF pair 5.			
	OL3#	111	1 = tri-state outputs, 0 = enable outputs			
36	OE6#	IN	Active low input for enabling DIF pair 6.			
			1 = tri-state outputs, 0 = enable outputs			
37	DIF_6#	OUT	0.7V differential complement clock output			
38	DIF_6	OUT	0.7V differential true clock output			
39	VDD	PWR	Power supply, nominal 3.3V			
40	OE_INV	IN	This latched input selects the polarity of the OE pins. 0 = OE pins active high, 1 = OE pins active low (OE#)			
41	DIF_7#	OUT	0.7V differential complement clock output			
42	DIF_7	OUT	0.7V differential true clock output			
43	OE4#	IN	Active low input for enabling DIF pair 4 1 = tri-state outputs, 0 = enable outputs			
44	OE7#	IN	Active low input for enabling DIF pair 7. 1 = tri-state outputs, 0 = enable outputs			
45	LOCK	OUT	3.3V output indicating PLL Lock Status. This pin goes high when lock is achieved.			
46	IREF	IN	This pin establishes the reference current for the differential current-mode output pairs. This pin requires a fixed precision resistor tied to ground in order to establish the appropriate current. 475 ohms is the standard value.			
47	GNDA	PWR	Ground pin for the PLL core.			
48	VDDA	PWR	3.3V power for the PLL core.			

Absolute Max

Symbol	Parameter	Min	Max	Units
VDD_A	3.3V Core Supply Voltage		4.6	V
VDD_In	3.3V Logic Supply Voltage		4.6	V
V_{IL}	Input Low Voltage	GND-0.5		V
V_{IH}	Input High Voltage		V _{DD} +0.5V	V
Ts	Storage Temperature	-65	150	°C
Tambient	Ambient Operating Temp	-40	85	°C
Tcase	Case Temperature		115	°C
	Input ESD protection			
ESD prot	human body model	2000		V

Electrical Characteristics - Input/Supply/Common Output Parameters

 $T_A = -40 - 85^{\circ}C$; Supply Voltage $V_{DD} = 3.3 \text{ V} + /-5\%$

$I_A = -40 - 65 C$, Supply V	Ortage VDD -	- 0.0 V +/-070					
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Input High Voltage	V_{IH}	3.3 V +/-5%	2		$V_{DD} + 0.3$	V	
Input Low Voltage	V_{IL}	3.3 V +/-5%	GND - 0.3		0.8	٧	
Input High Current	I _{IH}	$V_{IN} = V_{DD}$	-5		5	uA	
Input Low Current	I _{IL1}	$V_{IN} = 0 \text{ V}$; Inputs with no pull-up resistors	-5			uA	
	I _{IL2}	V _{IN} = 0 V; Inputs with pull-up resistors	V +/-5% GND - 0.3 0.8 V = V _{DD} -5 5 uA ith no pull-up resistors -5 uA with pull-up resistors -200 uA C _L = Full load; 200 mA lairs driven 60 mA I pairs tri-stated 6 mA Mode 50 110 MHz 1 ss Mode 50 400 MHz 1 c Inputs 1.5 5 pF 1 c capacitance 6 pF 1 when PLL_BW=0 2 3 4 MHz 1 o and after input clock sesertion of PD# to 1st lock 1 ms 1,2 r Modulation 30 33 kHz 1 t enable after 4d-assertion 10 ns 1,3 t enable after 300 us 1,3				
Operating Supply Current	I _{DD3.3OP}	Full Active, C _L = Full load;			200	mA	
Powerdown Current	l	all diff pairs driven			60	0 mA 0 mA 0 mA 0 MHz 0 MHz 0 MHz 7 nH 0 pF 0 pF	
1 OWEIGOWII CUITEIIL	I _{DD3.3PD}	all differential pairs tri-stated			6	mA	
Input Frequency	F _{iPLL}	PLL Mode	50		110	MHz	1
input i requericy	F _{iBYPASS}	Bypass Mode	50		400	MHz	1
Pin Inductance	L_{pin}				7	nΗ	1
Conscitones	C _{IN}	Logic Inputs	1.5		5	рF	1
Capacitance	C _{OUT}	Output pin capacitance			6	рF	1
PLL Bandwidth	BW	PLL Bandwidth when PLL_BW=0	2	3	4	MHz	1
T LL Dandwidth	DVV	PLL Bandwidth when PLL_BW=1	0.7	1	1.4	MHz	1
		From V _{DD} Power-Up and after input clock					
Clk Stabilization	T _{STAB}	stabilization or de-assertion of PD# to 1st			1	ms	1,2
		clock					
Modulation Frequency	f _{MOD}	Triangular Modulation	30		33	kHz	1
Tdrive_SRC_STOP#	t _{DRVSTP}	DIF output enable after SRC_Stop# de-assertion			10	ns	1,3
Tdrive_PD#	t _{DRVPD}	DIF output enable after PD# de-assertion			300	us	1,3
Tfall	t _F	Fall time of PD# and SRC_STOP#			5	ns	1
Trise	t _R	Rise time of PD# and SRC_STOP#			5	ns	2

¹Guaranteed by design and characterization, not 100% tested in production.

²See timing diagrams for timing requirements.

³Time from deassertion until outputs are >200 mV

Electrical Characteristics - Clock Input Parameters

 $T_A = -40 - 85$ °C; Supply Voltage $V_{DD} = 3.3 \text{ V } +/-5\%$

· A	enage i DD						
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Input High Voltage - DIF_IN	V _{IHDIF}	Differential inputs (single-ended measurement)	600	800	1150	mV	1
Input Low Voltage - DIF_IN	V _{ILDIF}	Differential inputs (single-ended measurement)	V _{SS} - 300	0	300	mV	1
Input Common Mode Voltage - DIF_IN	V _{COM}	Common Mode Input Voltage	300		1000	mV	1
Input Amplitude - DIF_IN	V _{SWING}	Peak to Peak value	300		1450	mV	1
Input Slew Rate - DIF_IN	dv/dt	Measured differentially	0.4		8	V/ns	1,2
Input Leakage Current	I _{IN}	$V_{IN} = V_{DD}$, $V_{IN} = GND$	-5		5	uA	1
Input Duty Cycle	d _{tin}	Measurement from differential wavefrom	45		55	%	1
Input Jitter - Cycle to Cycle	J_{DIFIn}	Differential Measurement	0		125	ps	1

¹ Guaranteed by design and characterization, not 100% tested in production.

²Slew rate measured through Vswing min centered around differential zero

Electrical Characteristics - DIF 0.7V Current Mode Differential Pair

 $T_A = -40 - 85^{\circ}C; V_{DD} = 3.3 \text{ V +/-5\%}; C_L = 2pF, R_S = 33.2\Omega, R_P = 49.9\Omega, R_{REF} = 475\Omega$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	NOTES
Current Source Output Impedance	Zo ¹	$V_O = V_x$	3000			Ω	1
Voltage High	VHigh	Statistical measurement on single ended signal	660		850	mV	1,3
Voltage Low	VLow	using oscilloscope math function.	-150		150	IIIV	1,3
Max Voltage	Vovs	Measurement on single ended signal using			1150	mV	1
Min Voltage	Vuds	absolute value.	-300			1117	1
Crossing Voltage (abs)	Vcross(abs)		250		550	mV	1
Crossing Voltage (var)	d-Vcross	Variation of crossing over all edges			140	mV	1
Long Accuracy	ppm	see Tperiod min-max values			0	ppm	1,2
Rise Time	t _r	$V_{OL} = 0.175V, V_{OH} = 0.525V$	175		700	ps	1
Fall Time	t _f	$V_{OH} = 0.525V V_{OL} = 0.175V$	175		700	ps	1
Rise Time Variation	d-t _r				125	ps	1
Fall Time Variation	d-t _f				125	ps	1
Duty Cycle	d_{t3}	Measurement from differential wavefrom	45	50	55	%	1
Skew	t _{sk3}	$V_{T} = 50\%$			60	ps	1
Jitter, Cycle to cycle	t.	PLL mode		40	50	ps	1,5
ontier, Oycle to cycle	t _{jcyc-cyc}	BYPASS mode as additive jitter		15	50	ps	1,5
		PCIe Gen 1 specs (pk to pk value)		30	86	ps	1,6,7
Jitter, Phase	tjphasebypass	PCIe Gen 2 specs (rms value)		2.6	3.1	ps	1,6,7
		PCIe Gen 1 specs (pk to pk value)		40	86	ps	1,6,7
	t _{jphase} PLL	PCIe Gen 2 specs (rms value)		2.8	3.1	ps	1,6,7

¹Guaranteed by design and characterization, not 100% tested in production.

² All Long Term Accuracy specifications are guaranteed with the assumption that the input clock complies with CK409/CK410/CK505 accuracy requirements. The 9DB403/803 itself does not contribute to ppm error.

 $^{^{3}}I_{REF} = V_{DD}/(3xR_{R})$. For $R_{R} = 475\Omega$ (1%), $I_{REF} = 2.32$ mA. $I_{OH} = 6$ x I_{REF} and $V_{OH} = 0.7$ V @ $Z_{O} = 50\Omega$.

⁴ Applies to Bypass Mode Only

⁵ Measured from differential waveform

⁶ See http://www.pcisig.com for complete specs

⁷ Device driven by HP81134A Pulse Generator

Clock Periods Differential Outputs with Spread Spectrum Enabled

11111111	urement ndow	1 Clock	1us	0.1s	0.1s	0.1s	1us	1 Clock		
Sy	mbol	Lg-	-SSC	-ppm error	0ppm	+ ppm error	+SSC	Lg+	1	
		Absolute Period	Short-term Average	Long-Term Average	Period	Long-Term Average	Short-term Average	Period		
Def	inition	Minimum Absolute Period	Minimum Absolute Period	Minimum Absolute Period	Nominal	Maximum	Maximum	Maximum	Units	Notes
	DIF 100	9.87400	9.99900	9.99900	10.00000	10.00100	10.05130	10.17630	ns	1,2,3
e e	DIF 133	7.41425	7.49925	7.49925	7.50000	7.50075	7.53845	7.62345	ns	1,2,4
Name	DIF 166	5.91440	5.99940	5.99940	6.00000	6.00060	6.03076	6.11576	ns	1,2,4
 	DIF 200	4.91450	4.99950	4.99950	5.00000	5.00050	5.02563	5.11063	ns	1,2,4
Signal	DIF 266	3.66463	3.74963	3.74963	3.75000	3.75038	3.76922	3.85422	ns	1,2,4
Ś	DIF 333	2.91470	2.99970	2.99970	3.00000	3.00030	3.01538	3.10038	ns	1,2,4
	DIF 400	2.41475	2.49975	2.49975	2.50000	2.50025	2.51282	2.59782	ns	1,2,4

Clock Periods Differential Outputs with Spread Spectrum Disabled

Measurement				•						
Wi	ndow	1 Clock	1us	0.1s	0.1s	0.1s	1us	1 Clock		
Symbol		Lg-	-SSC	-ppm error	0ppm	+ ppm error	+SSC	Lg+		
Definition		Absolute Period	Short-term Average	Long-Term Average	Period	Long-Term Average	Short-term Average	Period		
		Minimum Absolute	Minimum Absolute	Minimum Absolute	Nominal	Maximum	Maximum	Maximum		
	•	Period	Period	Period					Units	Notes
	DIF 100	9.87400		9.99900	10.00000	10.00100		10.17630	ns	1,2,3
ခ	DIF 133	7.41425		7.49925	7.50000	7.50075		7.62345	ns	1,2,4
Name	DIF 166	5.91440		5.99940	6.00000	6.00060		6.11576	ns	1,2,4
 	DIF 200	4.91450		4.99950	5.00000	5.00050		5.11063	ns	1,2,4
Signal	DIF 266	3.66463		3.74963	3.75000	3.75038		3.85422	ns	1,2,4
Ś	DIF 333	2.91470		2.99970	3.00000	3.00030		3.10038	ns	1,2,4
	DIF 400	2.41475		2.49975	2.50000	2.50025		2.59782	ns	1,2,4

¹Guaranteed by design and characterization, not 100% tested in production.

² All Long Term Accuracy specifications are guaranteed with the assumption that the input clock complies with CK409/CK410/CK505 accuracy requirements. The 9DB403/803 itself does not contribute to ppm error.

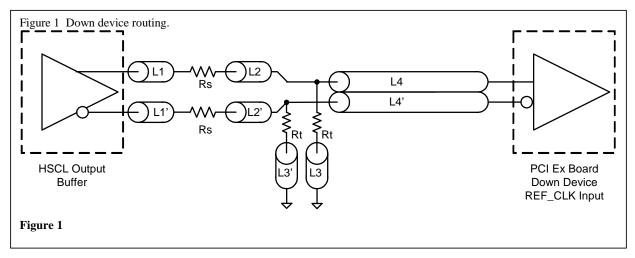
³ Driven by SRC output of main clock, PLL or Bypass mode

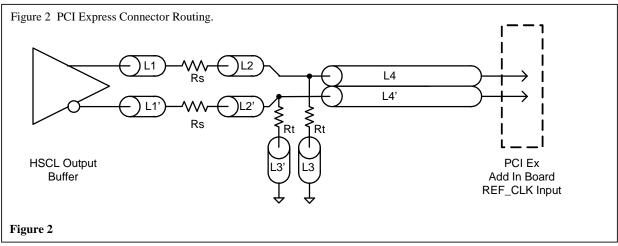
⁴ Driven by CPU output of CK410/CK505 main clock, **Bypass mode only**

SRC Reference Clock									
Common Recommendations for Differential Routing	Dimension or Value	Unit	Figure						
L1 length, Route as non-coupled 50 ohm trace.	0.5 max	inch	1						
L2 length, Route as non-coupled 50 ohm trace.	0.2 max	inch	1						
L3 length, Route as non-coupled 50 ohm trace.	0.2 max	inch	1						
Rs	33	ohm	1						
Rt	49.9	ohm	1						

Down Device Differential Routing	Dimension or Value	Unit	Figure
L4 length, Route as coupled microstrip 100 ohm differential trace.	2 min to 16 max	inch	1
L4 length, Route as coupled stripline 100 ohm differential trace.	1.8 min to 14.4 max	inch	1

Differential Routing to PCI Express Connector	Dimension or Value	Unit	Figure
L4 length, Route as coupled microstrip 100 ohm differential trace.	0.25 to 14 max	inch	2
L4 length, Route as coupled stripline 100 ohm differential trace.	0.225 min to 12.6 max	inch	2

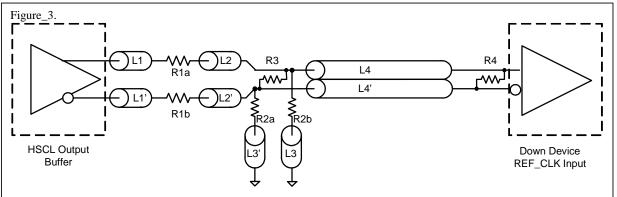




Alternative termination for LVDS and other common differential signals. Figure 3.

Vdiff	Vp-p	Vcm	R1	R2	R3	R4	Note
0.45 v	0.22v	1.08	33	150	100	100	
0.58	0.28	0.6	33	78.7	137	100	
0.80	0.40	0.6	33	78.7	none	100	ICS874003i-02 input compatible
0.60	0.3	1.2	33	174	140	100	Standard LVDS

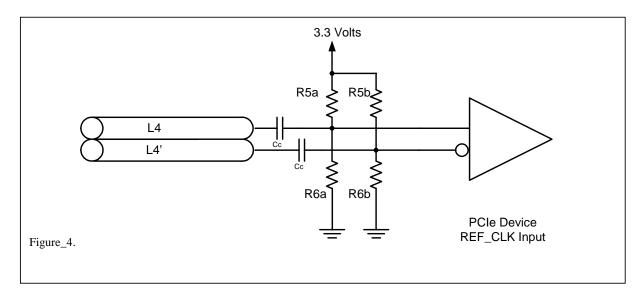
R1a = R1b = R1



R2a = R2b = R2

Cable connected AC coupled application, figure 4

Component	Value	Note
R5a,R5b	8.2K 5%	
R6a,R6b	1K 5%	
Сс	0.1 uF	
Vcm	0.350 volts	



General SMBus serial interface information for the ICS9DB803DI

How to Write:

- · Controller (host) sends a start bit.
- Controller (host) sends the write address DC_(n)
- ICS clock will acknowledge
- Controller (host) sends the begining byte location = N
- ICS clock will acknowledge
- Controller (host) sends the data byte count = X
- ICS clock will acknowledge
- Controller (host) starts sending Byte N through Byte N + X -1
- ICS clock will acknowledge each byte one at a time
- · Controller (host) sends a Stop bit

How to Read:

- · Controller (host) will send start bit.
- Controller (host) sends the write address DC (h)
- ICS clock will acknowledge
- Controller (host) sends the begining byte location = N
- ICS clock will acknowledge
- Controller (host) will send a separate start bit.
- Controller (host) sends the read address DD (h)
- ICS clock will acknowledge
- ICS clock will send the data byte count = X
- ICS clock sends Byte N + X -1
- ICS clock sends Byte 0 through byte X (if X_(h) was written to byte 8).
- Controller (host) will need to acknowledge each byte
- Controllor (host) will send a not acknowledge bit
- · Controller (host) will send a stop bit

Ind	ex Block W	/rit	e Operation
Cor	ntroller (Host)		ICS (Slave/Receiver)
Т	starT bit		
Slav	e Address DC _(h)		
WR	WRite		
		ACK	
Begi	nning Byte = N		
		ACK	
Data	Byte Count = X		
		ACK	
Begir	nning Byte N		
			ACK
	\rightarrow	ţe	
	\rightarrow	Byte	\rightarrow
	\rightarrow	×	\Q
			\Q
Byte	e N + X - 1		
			ACK
Р	stoP bit		

Ind	ex Block Rea	ad	Operation		
Con	troller (Host)	IC	S (Slave/Receiver)		
T	starT bit				
Slave	Address DC _(h)				
WR	WRite				
		ACK			
Begir	nning Byte = N				
			ACK		
RT	Repeat starT				
Slave	Address DD _(h)				
RD	ReaD				
			ACK		
		Data Byte Count = X			
	ACK				
			Beginning Byte N		
	ACK				
		/te	\Q		
	O	X Byte	\Q		
	\Q	×	\Q		
	\Q				
			Byte N + X - 1		
N	Not acknowledge				
Р	stoP bit				

SMBus Table: Frequency Select Register, READ/WRITE ADDRESS (DC/DD)

				,				
By	yte 0	Pin #	Name	Control Function	Type	0	1	PWD
Bit 7	-		PD_Mode	PD# drive mode	RW	driven	Hi-Z	0
Bit 6	6 - STC		STOP_Mode	SRC_Stop# drive mode	RW	driven	Hi-Z	0
Bit 5	-		PD_Polarity	Select PD polarity	RW	Low	High	0
Bit 4	t 4 - Reser		Reserved	Reserved	RW	Reserved		Х
Bit 3	-		Reserved	Reserved		Res	erved	Х
Bit 2	-		PLL_BW#	Select PLL BW	RW	High BW	Low BW	1
Bit 1	-		BYPASS#	BYPASS#/PLL	RW	fan-out	ZDB	1
Bit 0	-		SRC DIV#	SRC Divide by 2 Select	RW	x/2	1x	1

SMBus Table: Output Control Register

В	/te 1	Pin #	Name	Control Function	Type	0	1	PWD		
Bit 7	42,4	41	DIF 7	Output Control	RW	Disable	Enable	1		
Bit 6			DIF_6	Output Control	RW	Disable	Enable	1		
Bit 5			34,33		34,33 DIF 5 Output Control		RW	Disable	Enable	1
Bit 4	30,29		30,29 DIF_4 Output Control		RW	Disable	Enable	1		
Bit 3	20,2	21	DIF_3	Output Control		Disable	Enable	1		
Bit 2	16,1	17	DIF_2	Output Control	RW	Disable	Enable	1		
Bit 1	12,1	13	DIF_1	Output Control	RW	Disable	Enable	1		
Bit 0	8,9	9	DIF_0	Output Control	RW	Disable	Enable	1		

SMBus Table: Output Control Register

В	yte 2	Pin #	Name	Control Function	Туре	0	1	PWD		
Bit 7	42,	41	DIF_7	Output Control	RW	Free-run	Stoppable	0		
Bit 6	38,	37	DIF_6	Output Control	RW	Free-run	Stoppable	0		
Bit 5	t 5 34,33		5 34,33		DIF_5	Output Control		Free-run	Stoppable	0
Bit 4	4 30,29		DIF_4	Output Control		Free-run	Stoppable	0		
Bit 3	20,	20,21 DIF_3 Output Contro		Output Control	RW	Free-run	Stoppable	0		
Bit 2	16,	17	DIF_2	Output Control	RW	Free-run	Stoppable	0		
Bit 1	12,	13	DIF_1	Output Control	RW	Free-run	Stoppable	0		
Bit 0	8,	9	DIF_0	Output Control	RW	Free-run	Stoppable	0		

SMBus Table: Output Control Register

Ву	yte 3	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7	Bit 7		Reserved	RW	Reserved		Х	
Bit 6				Reserved		Reserved		Χ
Bit 5				Reserved	RW	Reserved		Х
Bit 4				Reserved	RW	W Reserved		Х
Bit 3				Reserved	RW	Res	erved	Х
Bit 2		Reserved		RW	Res	erved	Х	
Bit 1			•	Reserved	RW	/ Reserved		Х
Bit 0	Bit 0			Reserved	RW	Res	erved	X

SMBus Table: Vendor & Revision ID Register

Ву	rte 4	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7	-		RID3		R	-	-	Χ
Bit 6	-		RID2	REVISION ID	R	-	-	Χ
Bit 5	-		RID1		R	-	-	Χ
Bit 4	-		RID0		R	-	-	Χ
Bit 3	-		VID3	VENDOR ID	R	-	-	0
Bit 2	-		VID2		R	-	-	0
Bit 1	-		VID1		R	-	-	0
Bit 0	-		VID0		R	-	-	1

SMBus Table: DEVICE ID

Ву	/te 5	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7	-			Device ID 7 (MSB)	RW			0
Bit 6	-			Device ID 6	RW			Χ
Bit 5	-			Device ID 5	RW	Doving IF) is 83 Hex	Χ
Bit 4	-			Device ID 4	RW		803 and 43	0
Bit 3	-			Device ID 3	RW		9DB403	0
Bit 2	-	-		Device ID 2	RW] nex ioi	906403	0
Bit 1	-	- Device I		Device ID 1	RW			1
Bit 0	-			Device ID 0	RW			1

SMBus Table: Byte Count Register

Ву	/te 6	Pin #	Name	Control Function	Туре	0	1	PWD
Bit 7	-		BC7		RW	1	ı	0
Bit 6	-		BC6		RW	-	-	0
Bit 5	-		BC5	Writing to this register configures how	RW	1	1	0
Bit 4	-		BC4		RW	1	1	0
Bit 3	-		BC3	many bytes will be read back.	RW	1	1	0
Bit 2	-		BC2		RW	1	1	1
Bit 1	-		BC1		RW	1	1	1
Bit 0	-		BC0		RW	-	-	1

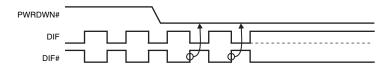
Note: Polarities in timing diagrams are shown OE_INV = 0. They are similar to OE_INV = 1.

PD#, Power Down

The PD# pin cleanly shuts off all clocks and places the device into a power saving mode. PD# must be asserted before shutting off the input clock or power to insure an orderly shutdown. PD is asynchronous active-low input for both powering down the device and powering up the device. When PD# is asserted, all clocks will be driven high, or tri-stated (depending on the PD# drive mode and Output control bits) before the PLL is shut down.

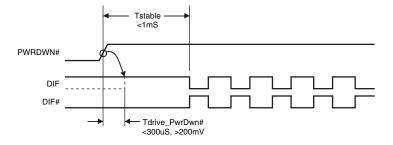
PD# Assertion

When PD# is sampled low by two consecutive rising edges of DIF#, all DIF outputs must be held High, or tri-stated (depending on the PD# drive mode and Output control bits) on the next High-Low transition of the DIF# outputs. When the PD# drive mode bit is set to '0', all clock outputs will be held with DIF driven High with 2 x I_{REF} and DIF# tri-stated. If the PD# drive mode bit is set to '1', both DIF and DIF# are tri-stated.



PD# De-assertion

Power-up latency is less than 1 ms. This is the time from de-assertion of the PD# pin, or VDD reaching 3.3V, or the time from valid SRC_IN clocks until the time that stable clocks are output from the device (PLL Locked). If the PD# drive mode bit is set to '1', all the DIF outputs must driven to a voltage of >200 mV within 300 us of PD# de-assertion.



SRC_STOP#

The SRC_STOP# signal is an active-low asynchronous input that cleanly stops and starts the DIF outputs. A valid clock must be present on SRC_IN for this input to work properly. The SRC_STOP# signal is de-bounced and must remain stable for two consecutive rising edges of DIF# to be recognized as a valid assertion or de-assertion.

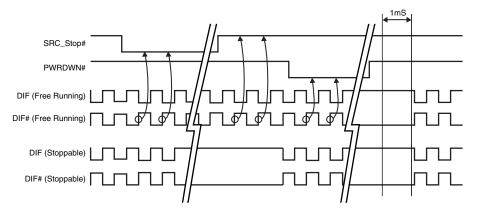
SRC STOP# - Assertion

Asserting SRC_STOP# causes all DIF outputs to stop after their next transition (if the control register settings allow the output to stop). When the SRC_STOP# drive bit is '0', the final state of all stopped DIF outputs is DIF = High and DIF# = Low. There is no change in output drive current. DIF is driven with $6x_{REF}$ DIF# is not driven, but pulled low by the termination. When the SRC_STOP# drive bit is '1', the final state of all DIF output pins is Low. Both DIF and DIF# are not driven.

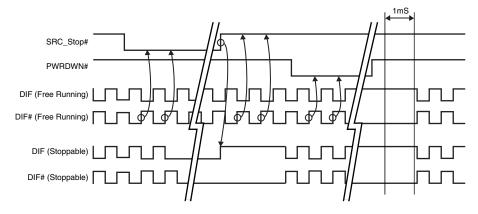
SRC_STOP# - De-assertion (transition from '0' to '1')

All stopped differential outputs resume normal operation in a glitch-free manner. The de-assertion latency to active outputs is 2-6 DIF clock periods, with all DIF outputs resuming simultaneously. If the SRC_STOP# drive control bit is '1' (tri-state), all stopped DIF outputs must be driven High (>200 mV) within 10 ns of de-assertion.

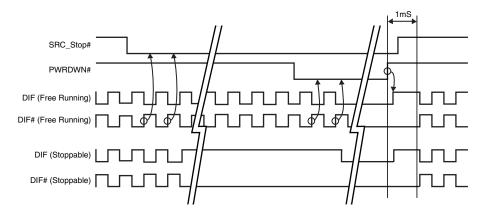
SRC_STOP_1 (SRC_Stop = Driven, PD = Driven)



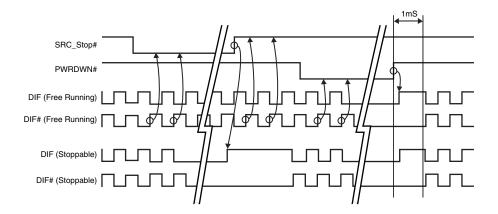
SRC_STOP_2 (SRC_Stop =Tristate, PD = Driven)

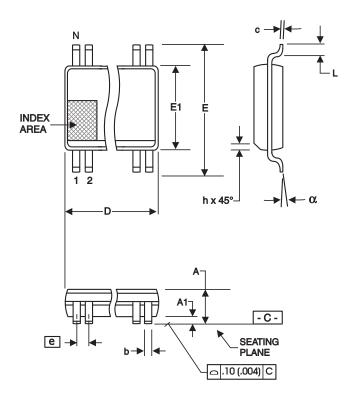


SRC_STOP_3 (**SRC_Stop** = **Driven**, **PD** = **Tristate**)



SRC_STOP_4 (SRC_Stop = Tristate, PD = Tristate)





	In Millir	neters	In Inches		
SYMBOL	COMMON D	IMENSIONS	COMMON DIMENSIONS		
	MIN	MAX	MIN	MAX	
Α	2.41	2.80	.095	.110	
A1	0.20	0.40	.008	.016	
b	0.20	0.34	.008	.0135	
С	0.13	0.25	.005	.010	
D	SEE VAR	IATIONS	SEE VARIATIONS		
E	10.03	10.68	.395	.420	
E1	7.40	7.60	.291	.299	
е	0.635 E	BASIC	0.025 BASIC		
h	0.38	0.64	.015	.025	
Ĺ	0.50	1.02	.020	.040	
N	SEE VARIATIONS		SEE VARIATIONS		
α	0°	8°	0°	8°	

VARIATIONS

N	D mm.		D (inch)	
IN	MIN	MAX	MIN	MAX
48	15.75	16.00	.620	.630

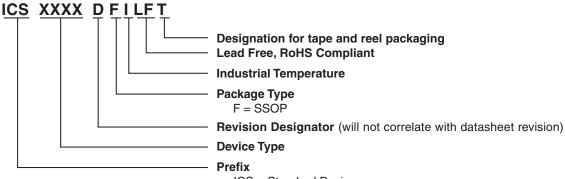
Reference Doc.: JEDEC Publication 95, MO-118

10-0034

Ordering Information

ICS9DB803DFILFT

Example:

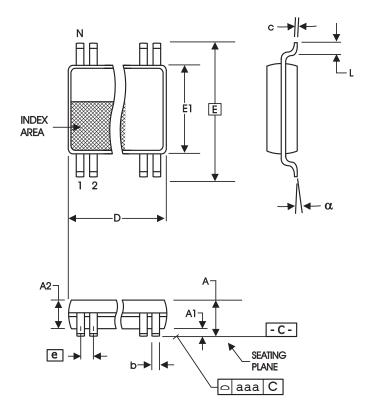


ICS = Standard Device

IDT™/ICS™ Eight Output Differential Buffer for PCIe Gen 2

ICS9DB803DI

REV A 06/18/08



48-Lead, 6.10 mm. Body, 0.50 mm. Pitch TSSOP (240 mil) (20 mil)

SYMBOL	In Millimeters COMMON DIMENSIONS		In Inches COMMON DIMENSIONS		
STIVIBUL	COMMON	INIENSIONS	COMMON	NIVIENSIONS	
	MIN	MAX	MIN	MAX	
Α		1.20		.047	
A1	0.05	0.15	.002	.006	
A2	0.80	1.05	.032	.041	
b	0.17	0.27	.007	.011	
С	0.09	0.20	.0035	.008	
D	SEE VAF	RIATIONS	SEE VARIATIONS		
E	8.10 E	BASIC	0.319 BASIC		
E1	6.00	6.20	.236	.244	
е	0.50 E	BASIC	0.020 BASIC		
L	0.45	0.75	.018	.030	
N	SEE VARIATIONS		SEE VARIATIONS		
а	0°	8°	0°	8°	
aaa		0.10		.004	

VARIATIONS

NI	D mm.		D (inch)		
N	MIN	MAX	MIN	MAX	
48	12.40	12.60	.488	.496	

Reference Doc.: JEDEC Publication 95, MO-153

10-0039

Ordering Information

ICS9DB803DGILFT

Example:



IDT™/ICS™ Eight Output Differential Buffer for PCIe Gen 2

ICS9DB803DI

REV A 06/18/08

Revision History

Rev.	Issue Date	Description	Page #
0.1	6/18/2008	1. Initial Release	Α

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